

Integrating remote sensing and citizen science to study the environmental context and ecological consequences of returning avian predators

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Animal predators in an urban World



Urban colonization



Accipiter Hawks



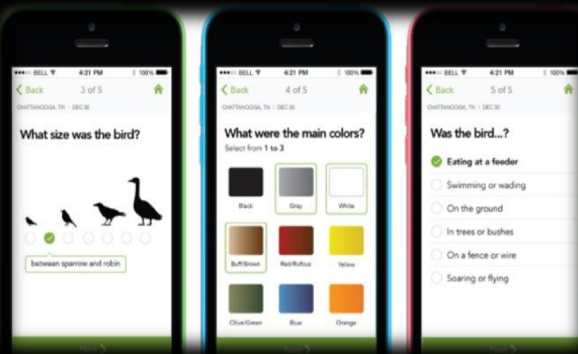
Is colonization driven by urban features?



Is colonization driven by prey availability?



Citizen science and urban ecology

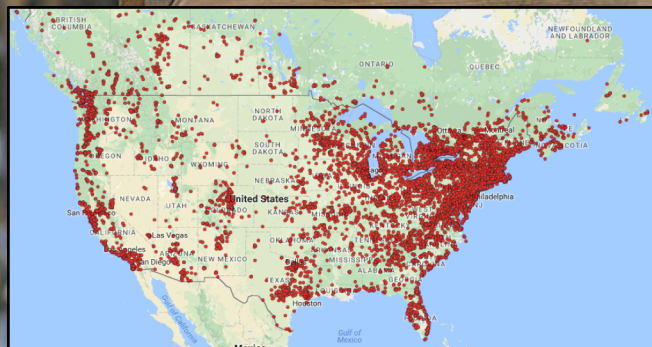


Citizen science: Project FeederWatch

1987-present (> 70,000 people)
Repeated counts ***November – April***

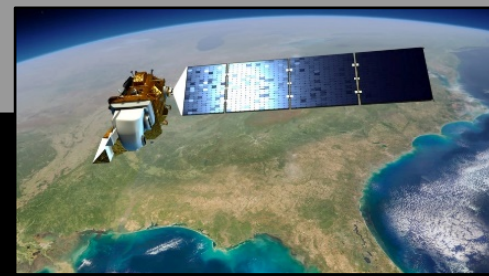
In 2016...

22,082 participants
140,034 checklists
6.8 million birds



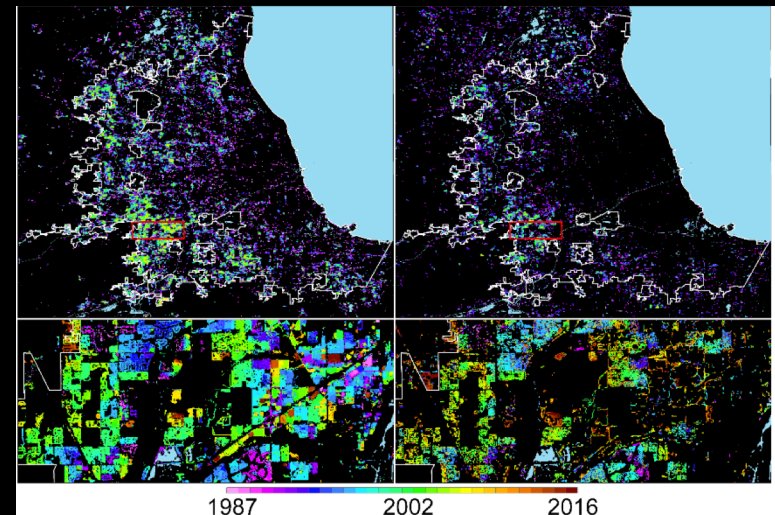
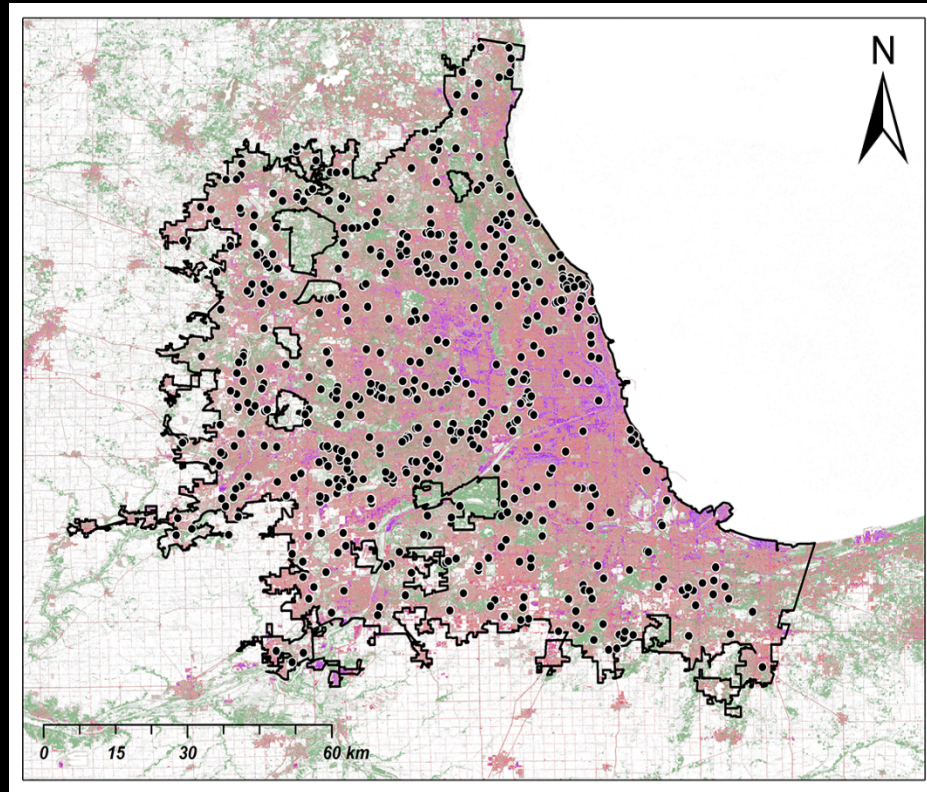
Occupancy Dynamics – (1996-2016)

$n = 554$



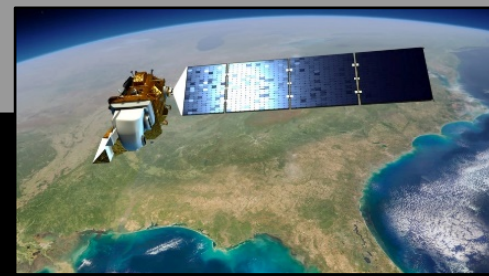
Landsat

- % imperviousness
- % tree canopy cover



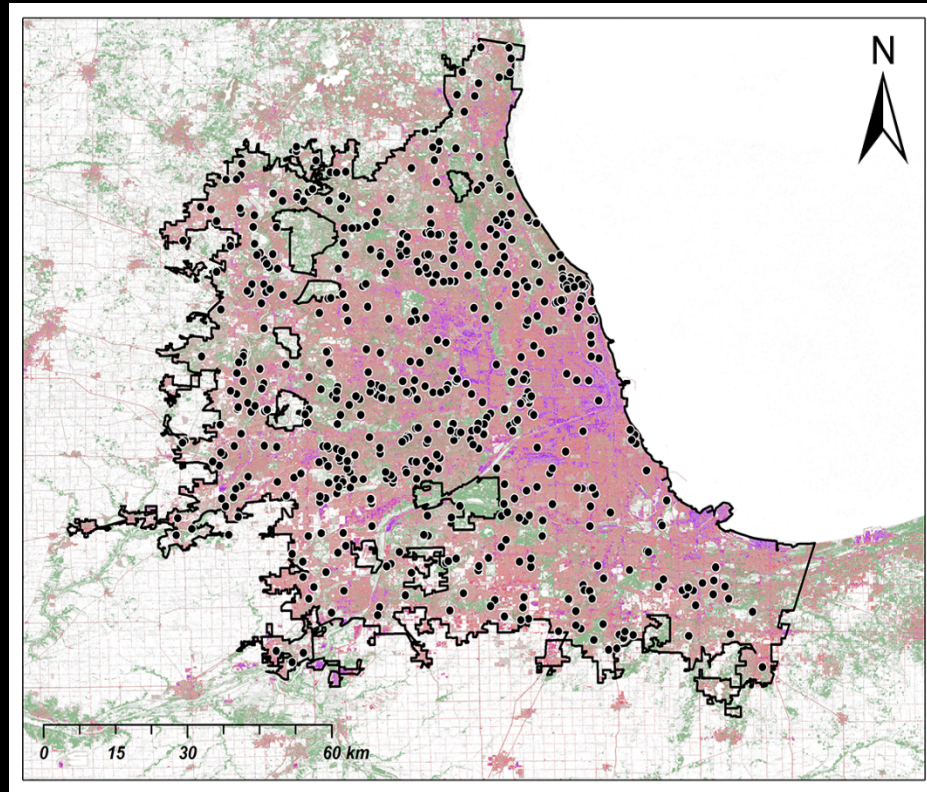
Occupancy Dynamics – (1996-2016)

$n = 554$



Landsat

- % imperviousness
- % tree canopy cover



3km buffer around sites (*Chiang et al. 2012*)

Prey availability



Dynamic Occupancy Model

Dynamic Occupancy Model

Detection Process



i = site; k = year; j = repeat survey (week)

Detection process:

$$\text{Logit}(p_{i,j,k}) = \tau_{\text{effort}[i,j,k]}$$

Dynamic Occupancy Model

Detection Process



$i = \text{site}; k = \text{year}; j = \text{repeat survey (week)}$

Detection process:

$$\text{Logit}(p_{i,j,k}) = \tau_{\text{effort}[i,j,k]} + \tau_1 * tmin_{i,j,k}$$

Dynamic Occupancy Model

Detection Process



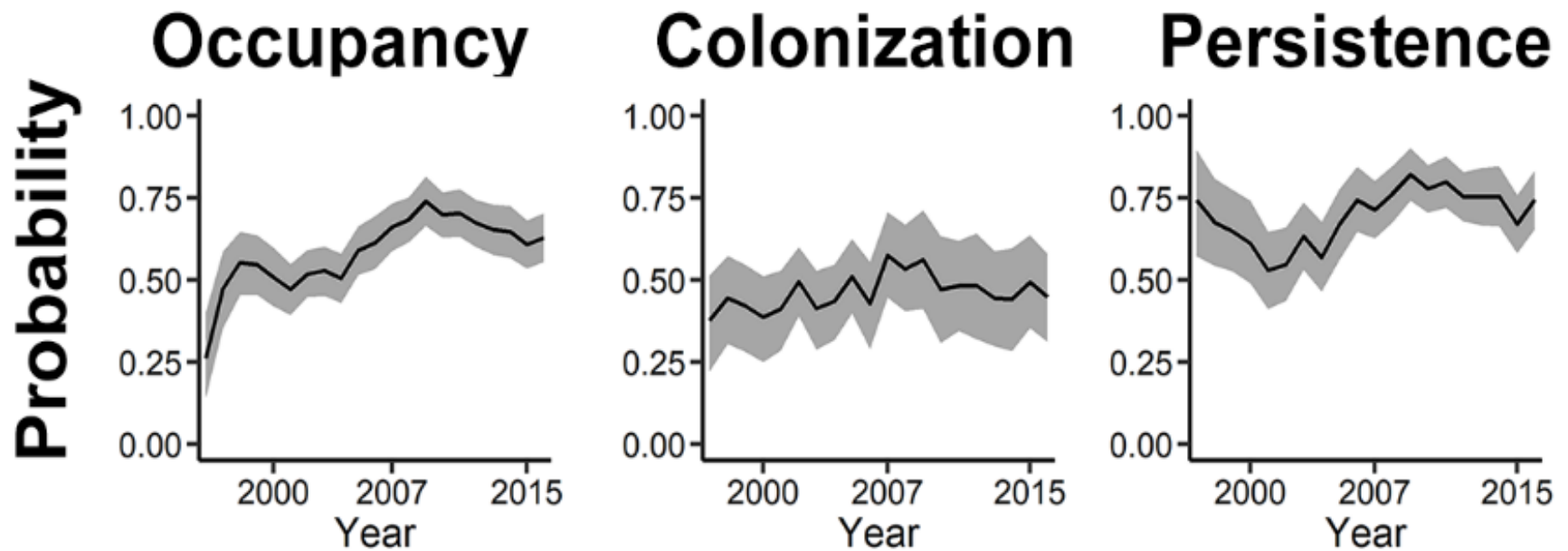
Ecological Process



Ecological process:

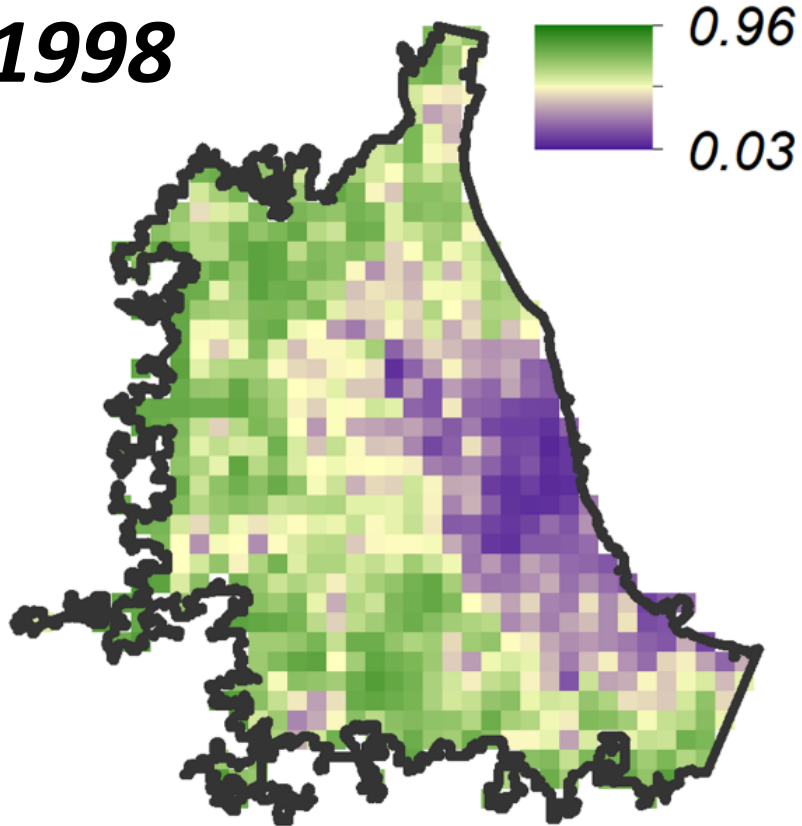
$$\begin{aligned}\text{Logit}(\phi_k) &= \beta_0 + \beta_1 * \text{treeCov}_i + \beta_2 * \text{ImpSur}_i + \beta_3 * \text{preyAbund}_{i,k} \\ \text{Logit}(\gamma_k) &= \alpha_0 + \alpha_1 * \text{treeCov}_i + \alpha_2 * \text{ImpSur}_i + \alpha_3 * \text{preyAbund}_{i,k_{1,i}}\end{aligned}$$

Occupancy Dynamics

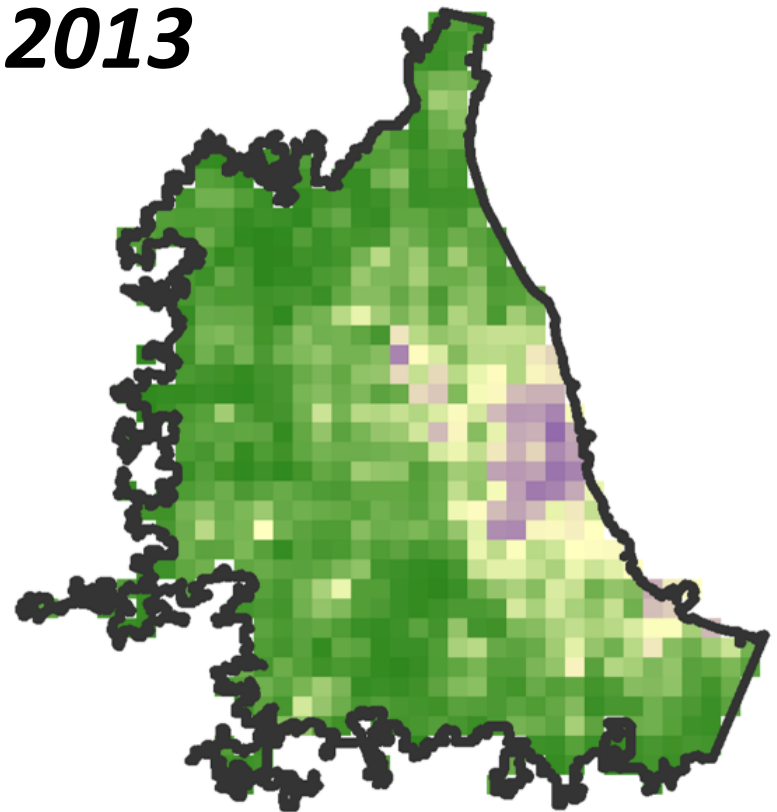


Occupancy Dynamics – *predictions*

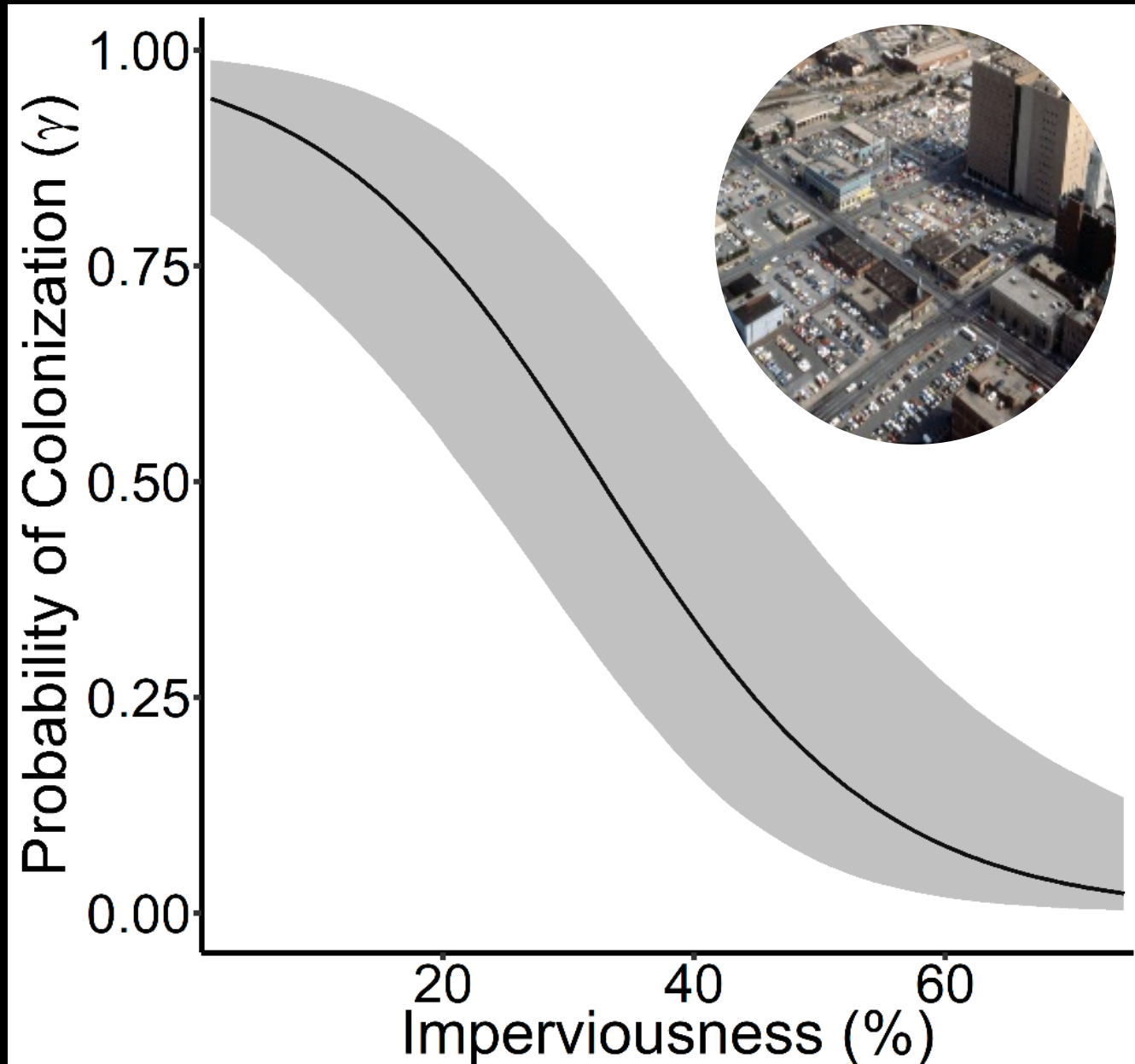
1998



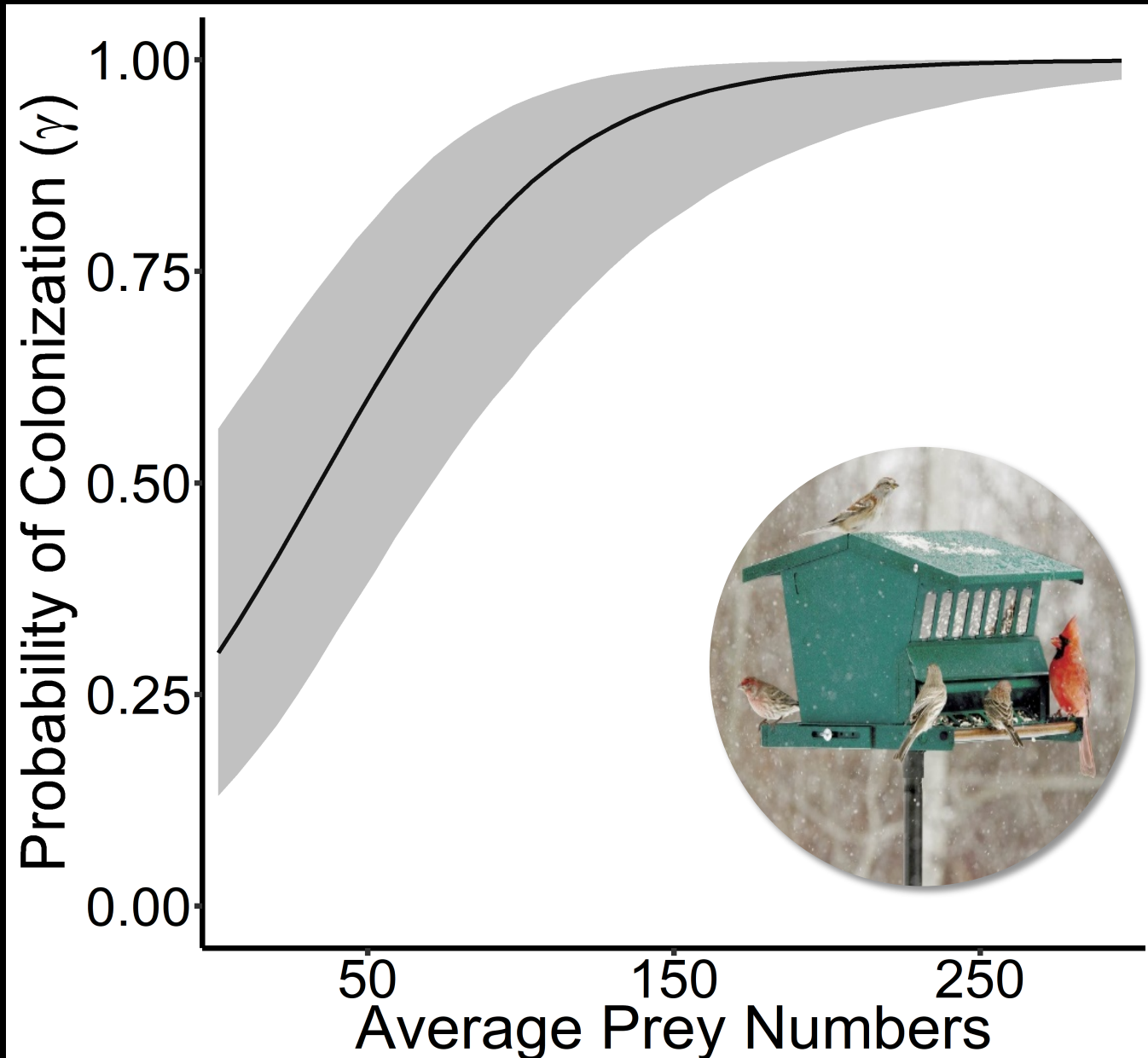
2013



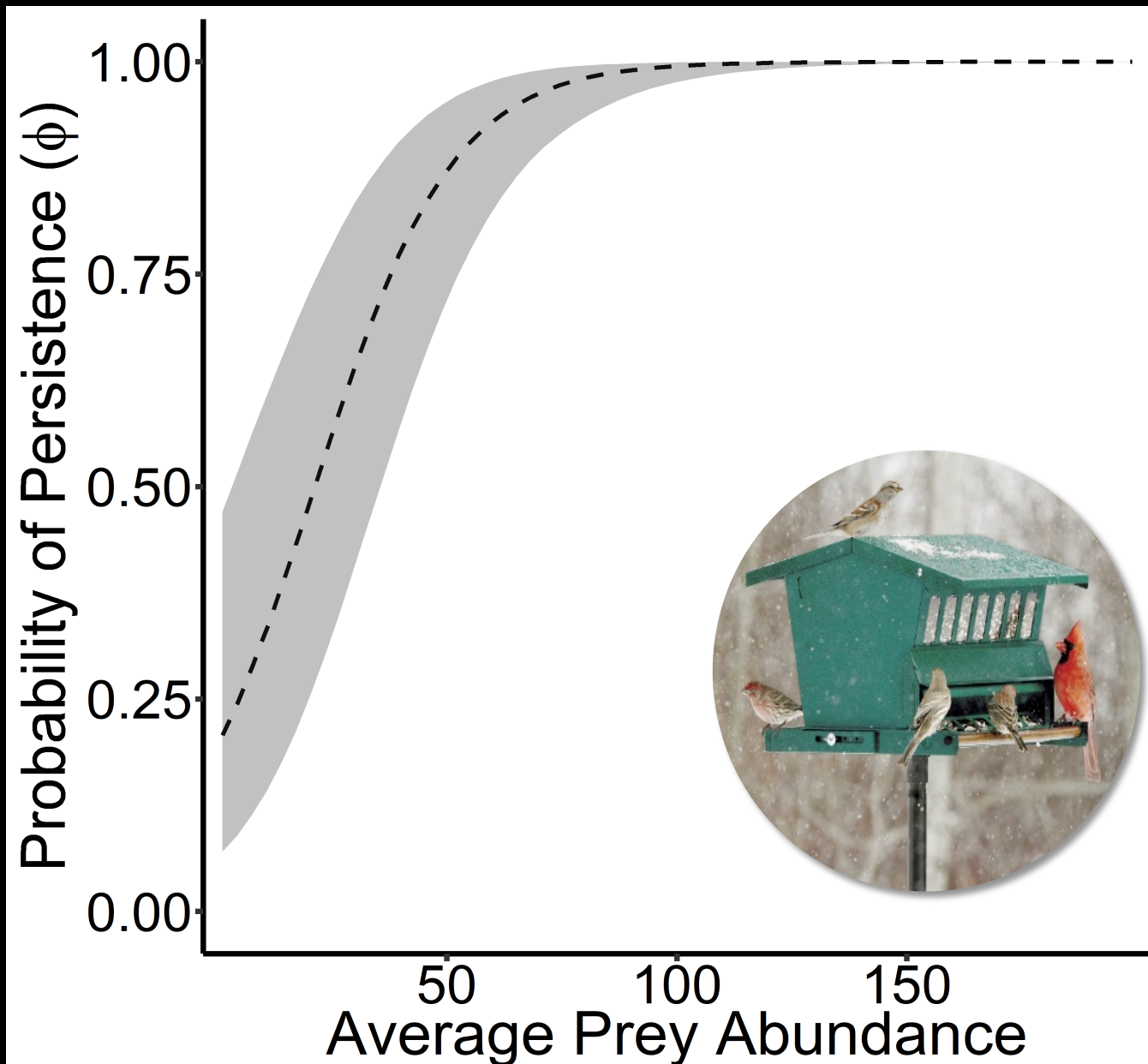
Occupancy Dynamics - *colonization*



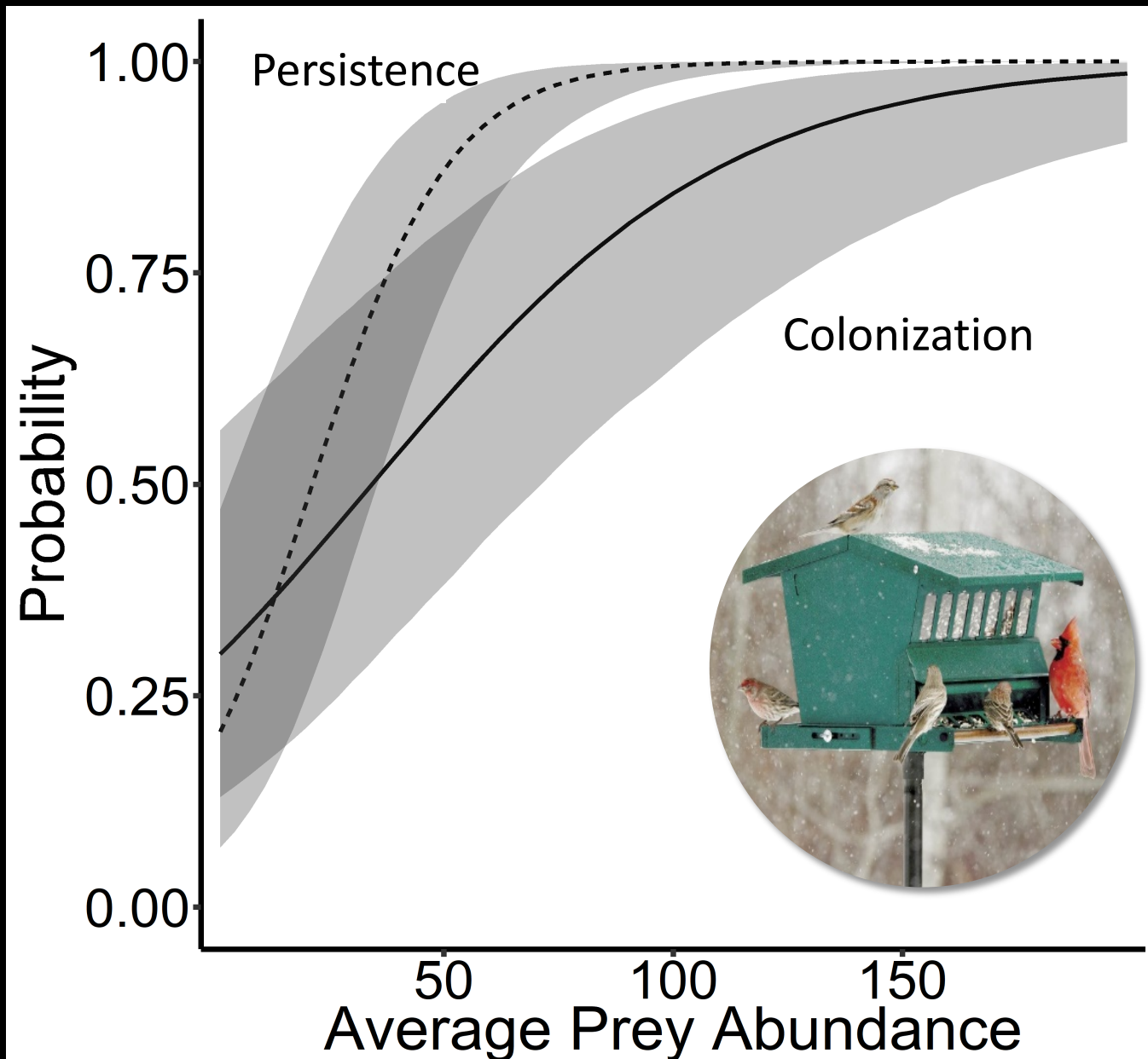
Occupancy Dynamics - *colonization*



Occupancy Dynamics - *persistence*



Occupancy Dynamics



Conclusions

Remote sensing can inform the study of urban colonization by animal predators

Hawks ***colonized*** along the outskirts of the city and were less likely to colonize areas of high ***imperviousness***

Once colonized, urban features play a less important role, persistence was ***dependent on prey***

Urban landscapes of fear – *predation risk*

Few failures are as unforgiving as the failure to avoid a predator:
being killed greatly decreases future fitness
(Lima and Dill 1990)



Citizen science meets behavioral ecology

Develop an approach for assessing antipredator behavior in birds that can be mass-deployed to citizen scientists



Antipredator behavior

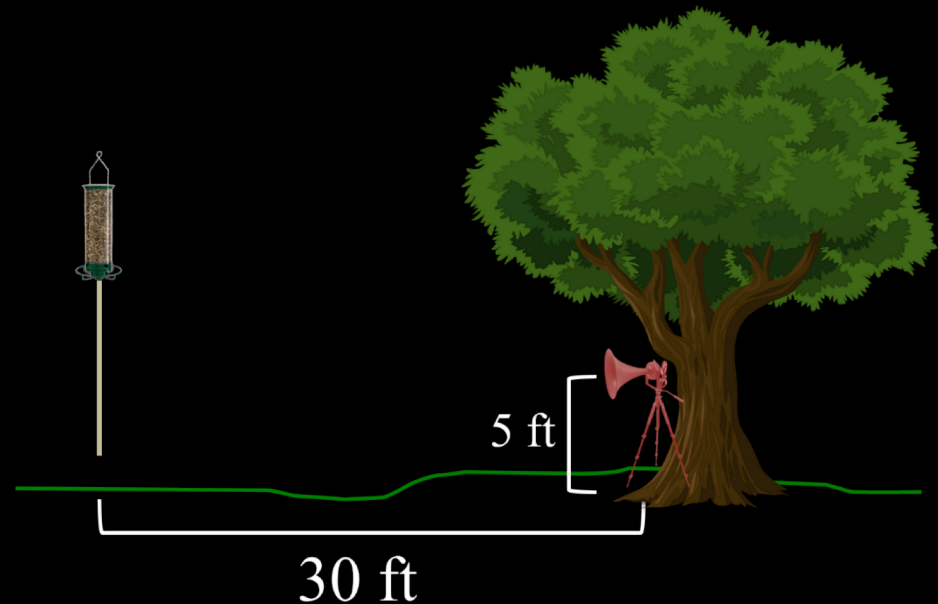
Playback experiment - “Hawk-Kits”

Predator stimulus

Antipredator behavior

Playback experiment - “Hawk-Kits”

Predator stimulus



Antipredator behavior

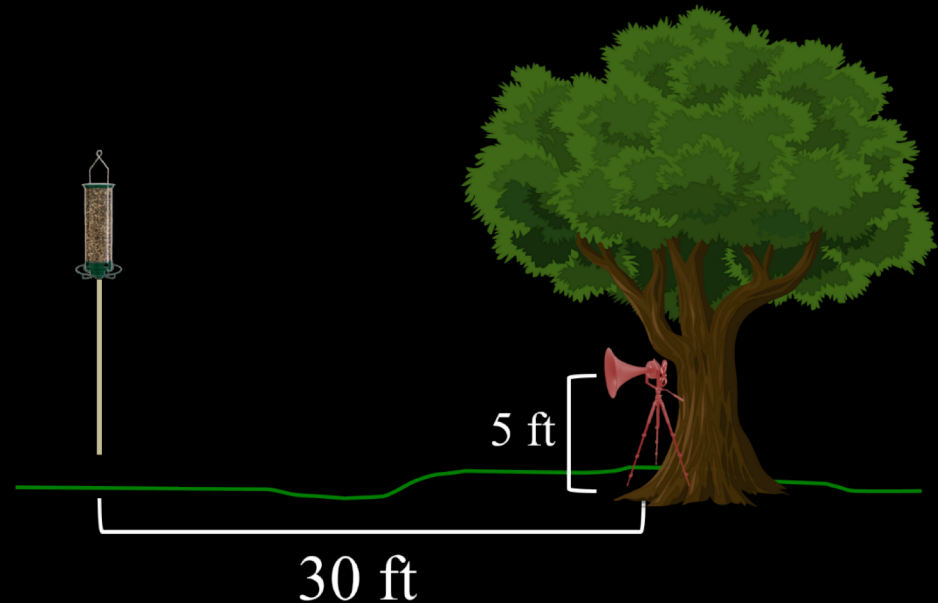
Playback experiment - “Hawk-Kits”

Predator stimulus

Control

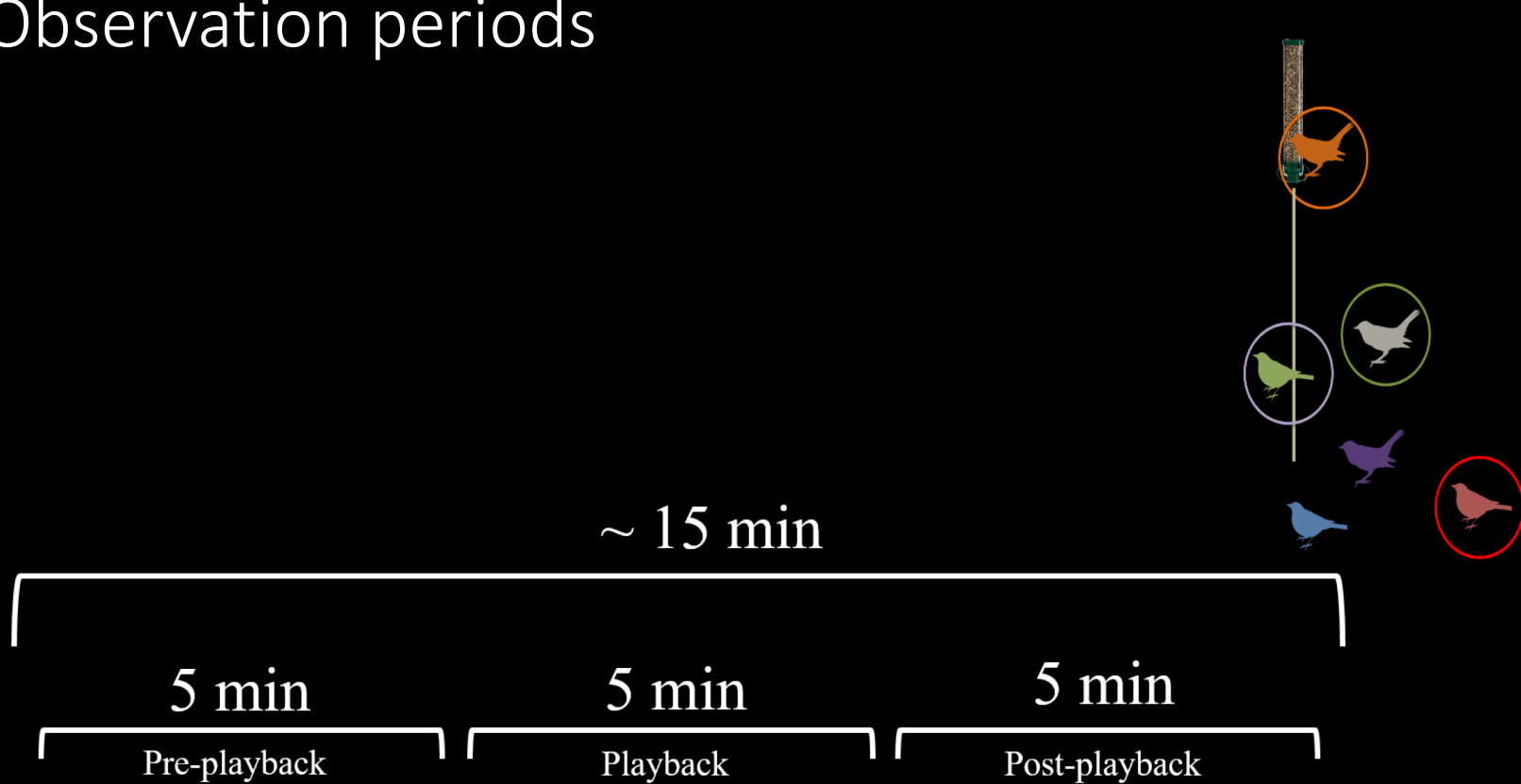


Treatment



Behavioral observations

Observation periods



Behavioral observations

Observation periods

Tally records

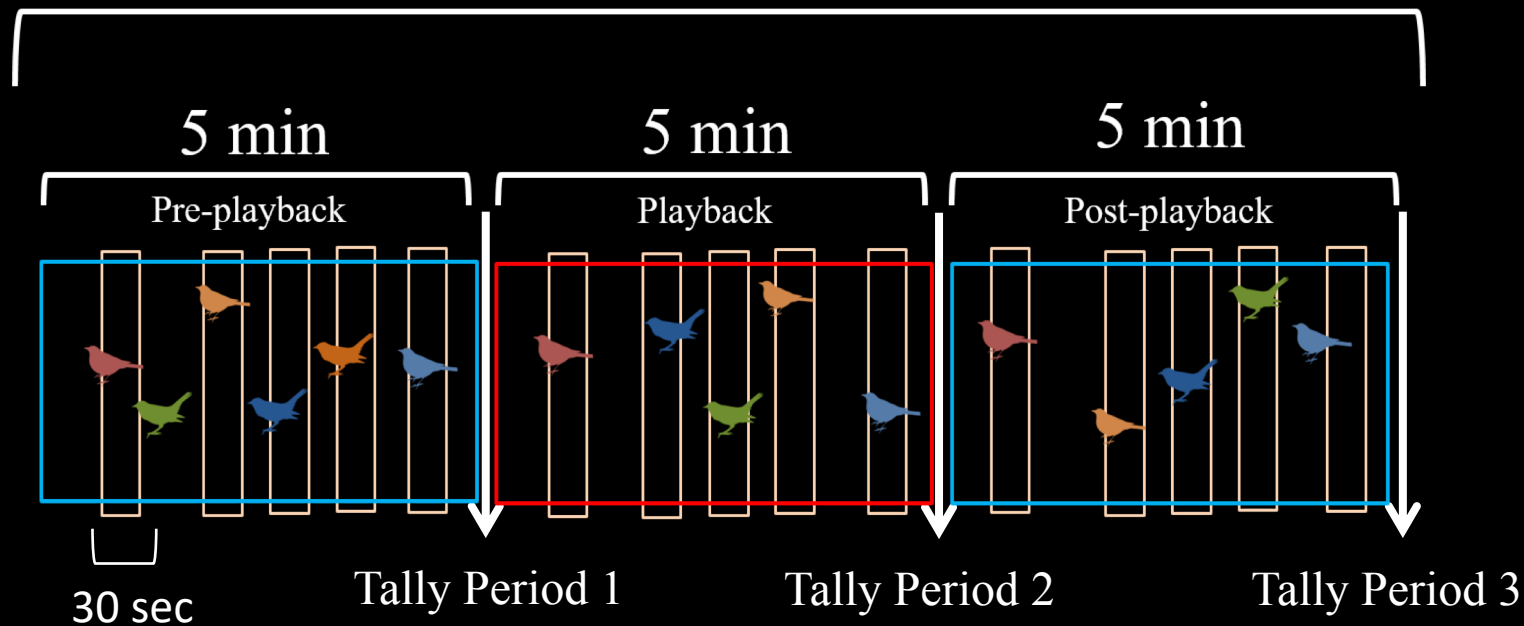
Counts of species

Behavioral observations

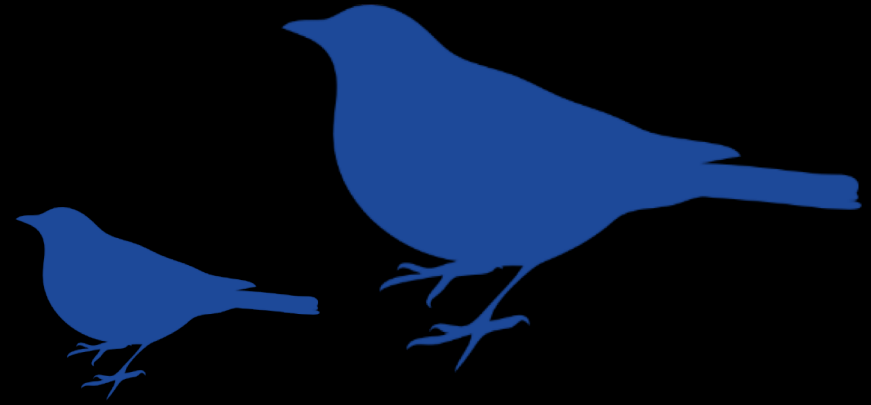
Head up and pecking



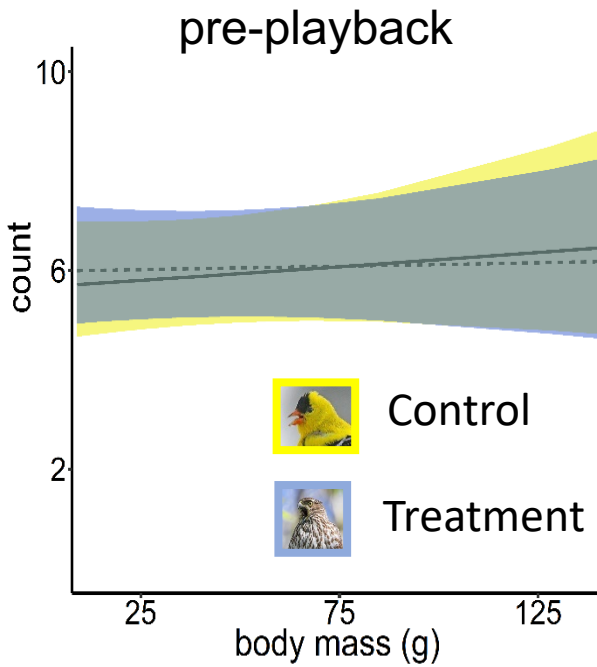
~ 15 min



Analysis

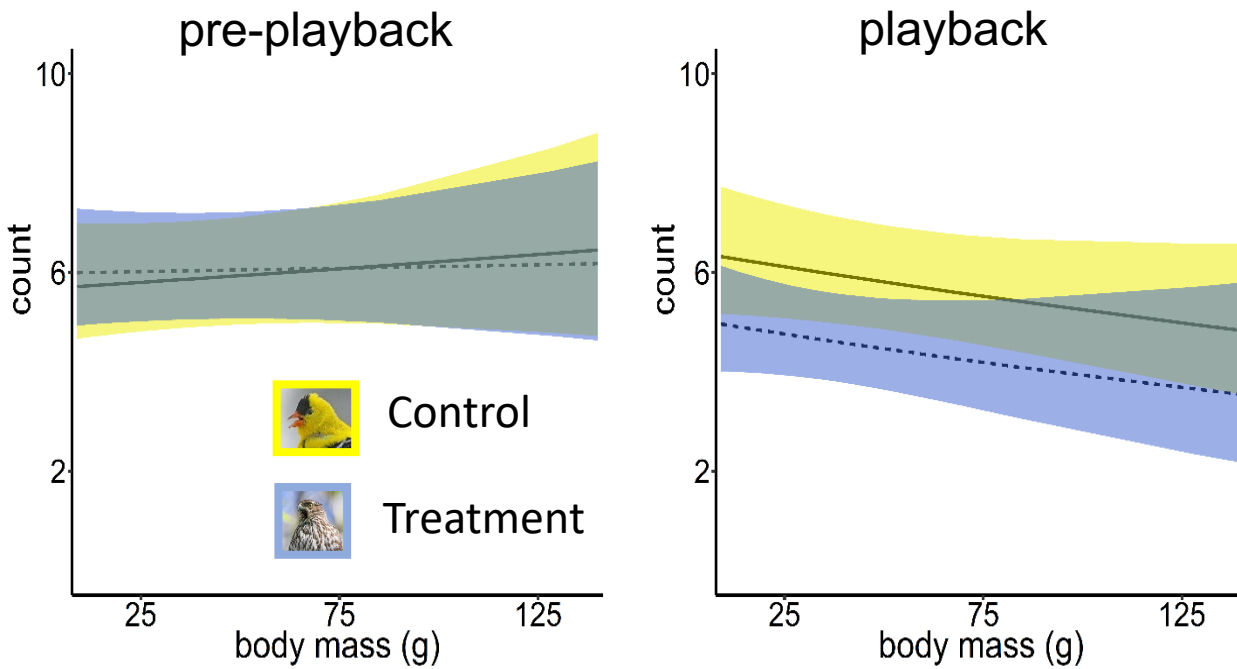


Flock Size



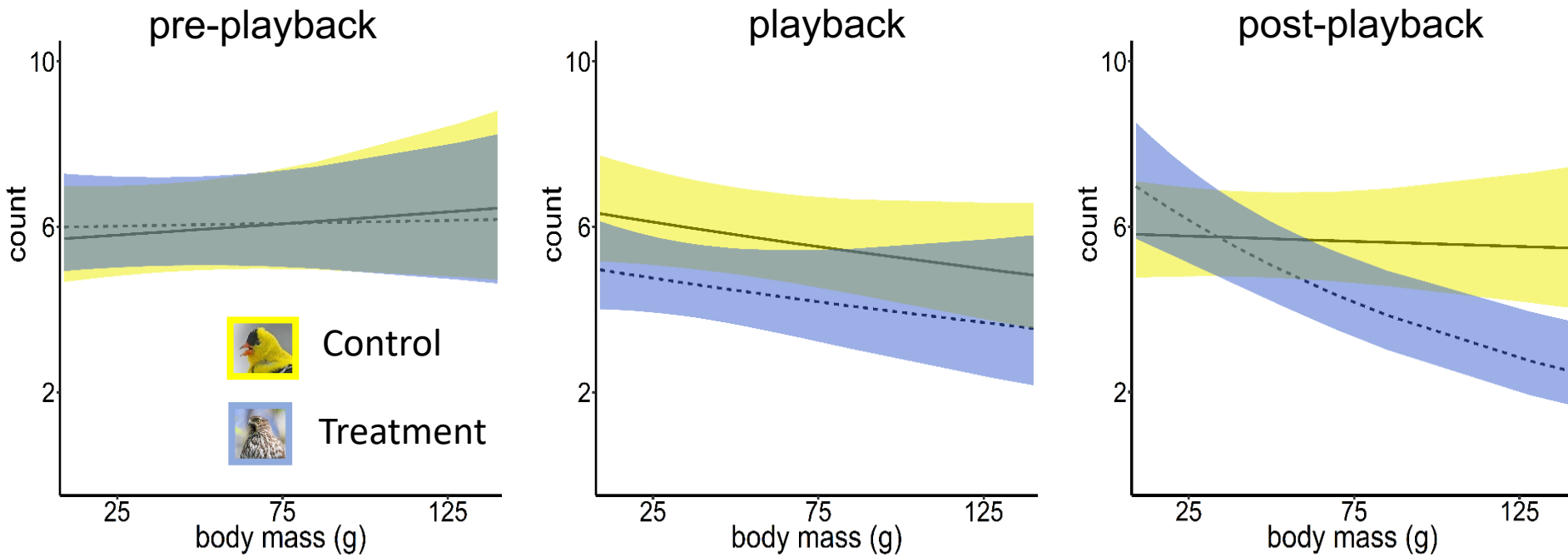
$n = 1089$

Flock Size

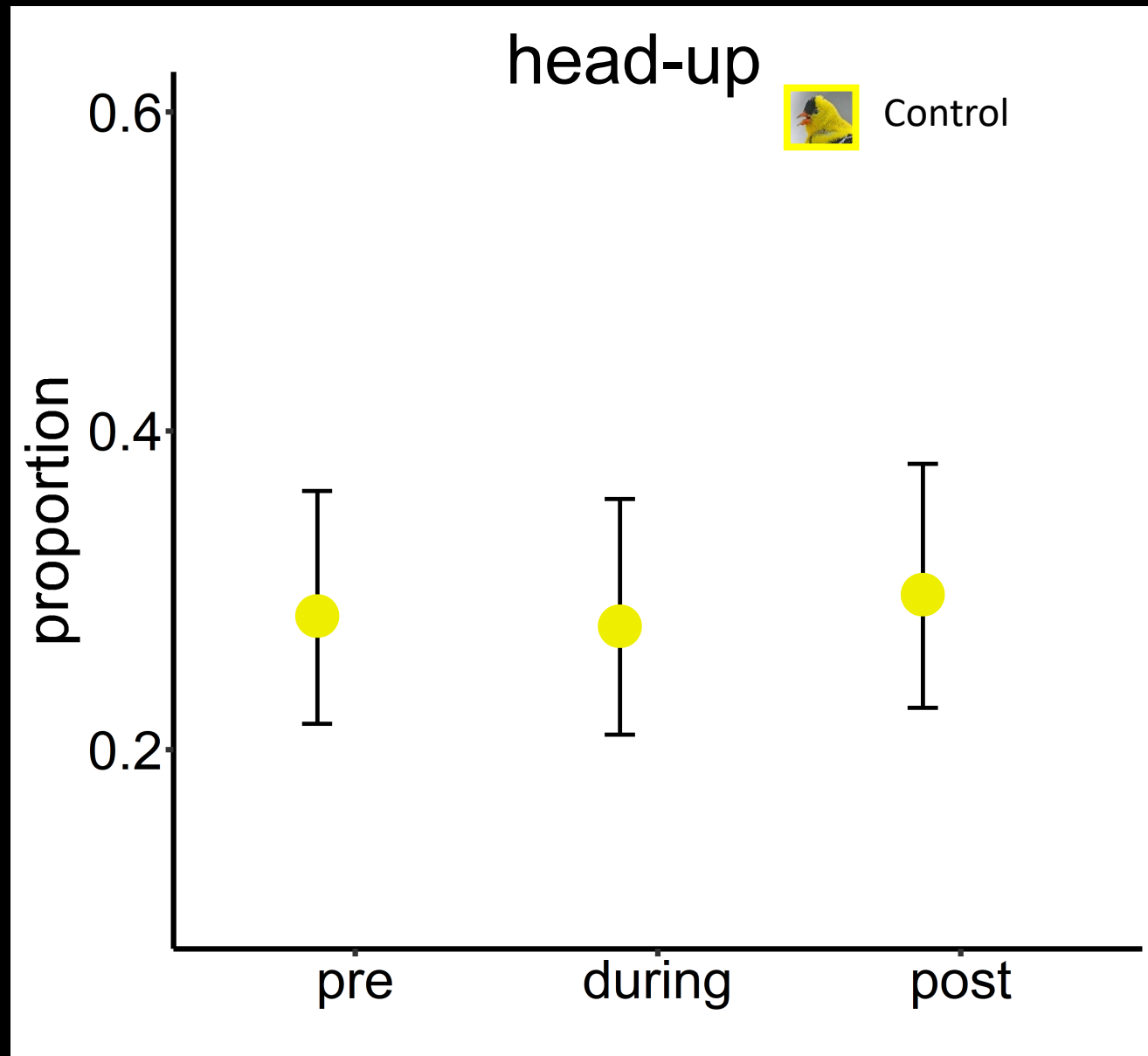


$n = 1089$

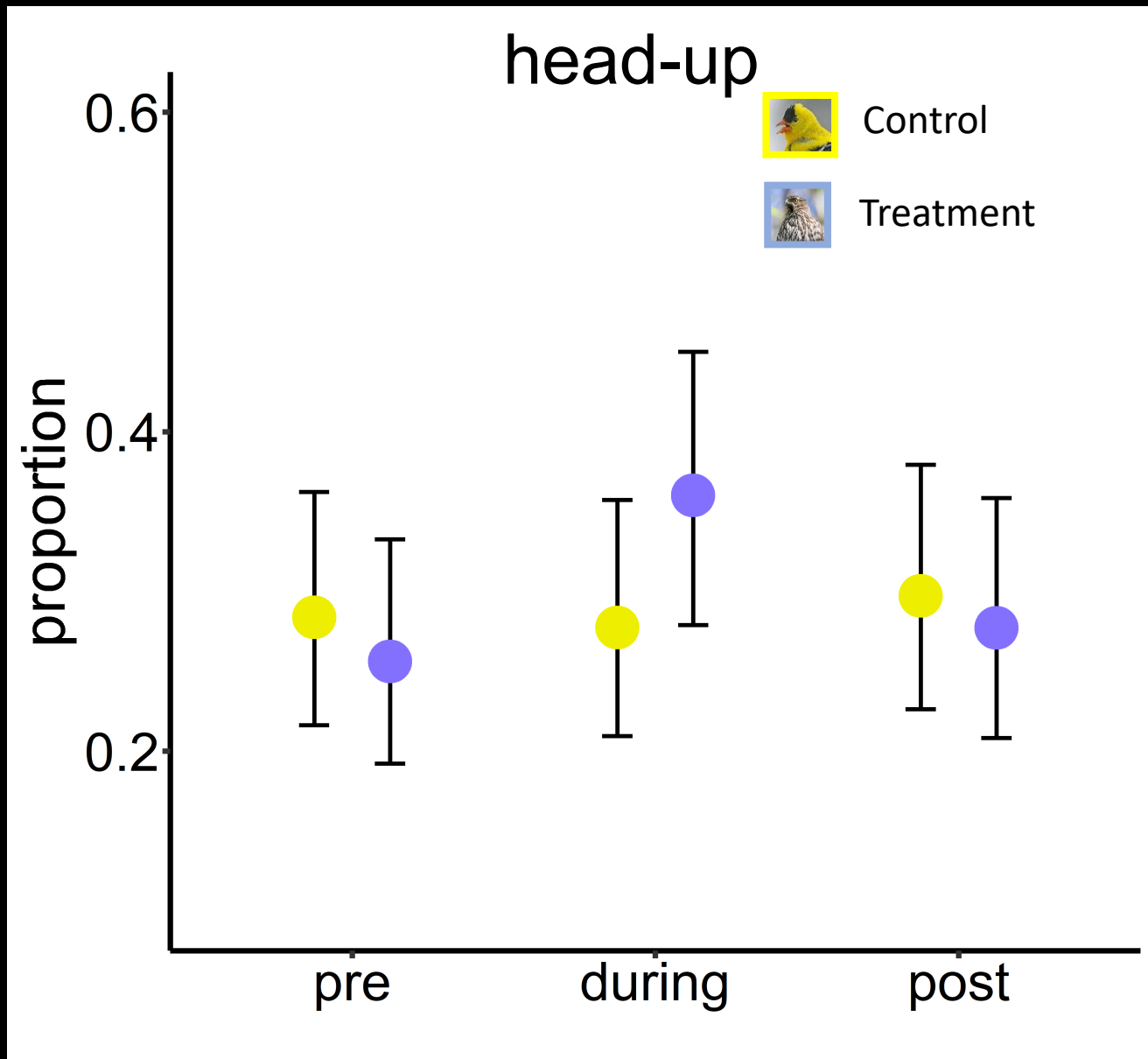
Flock Size

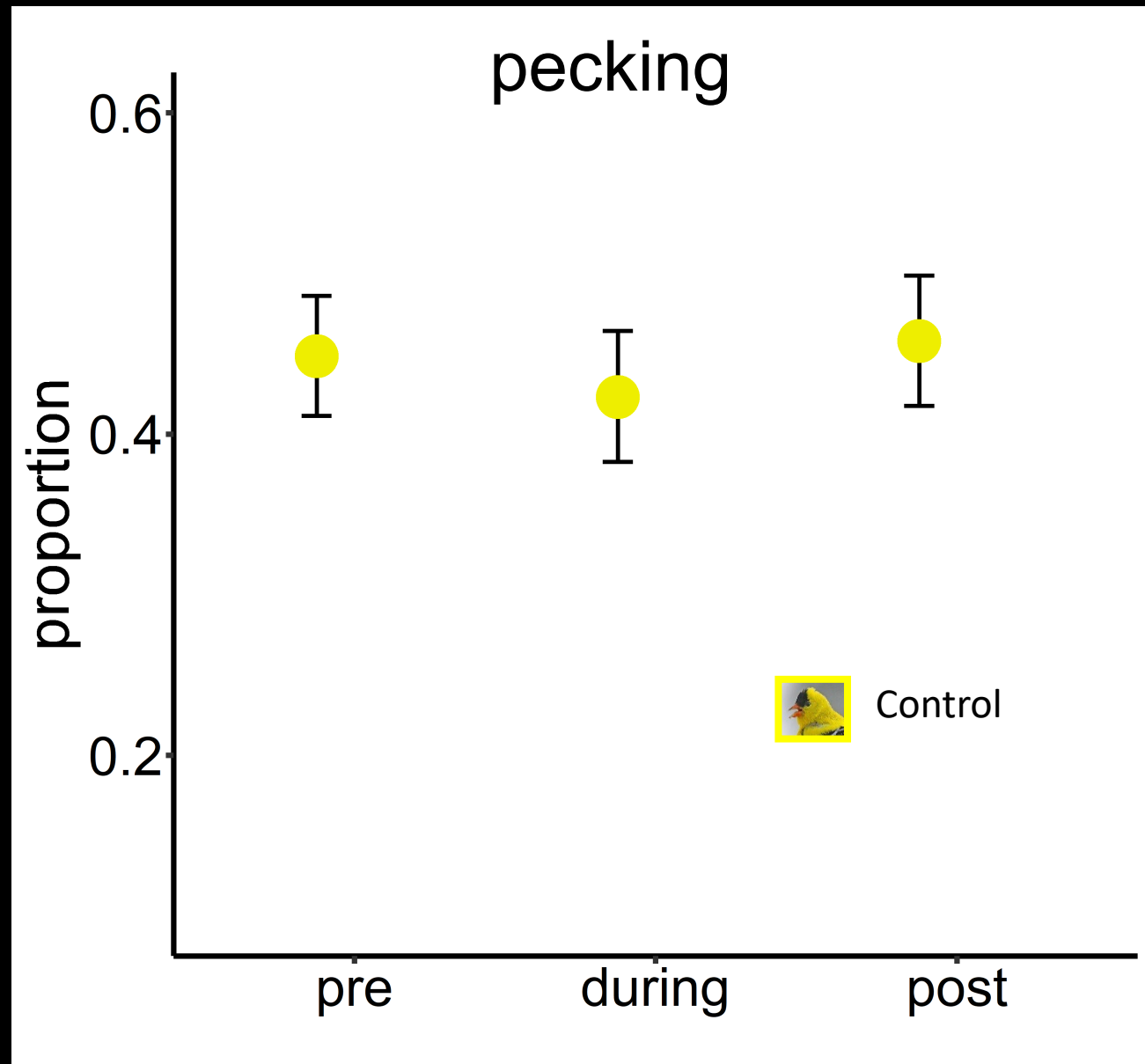


$n = 1089$

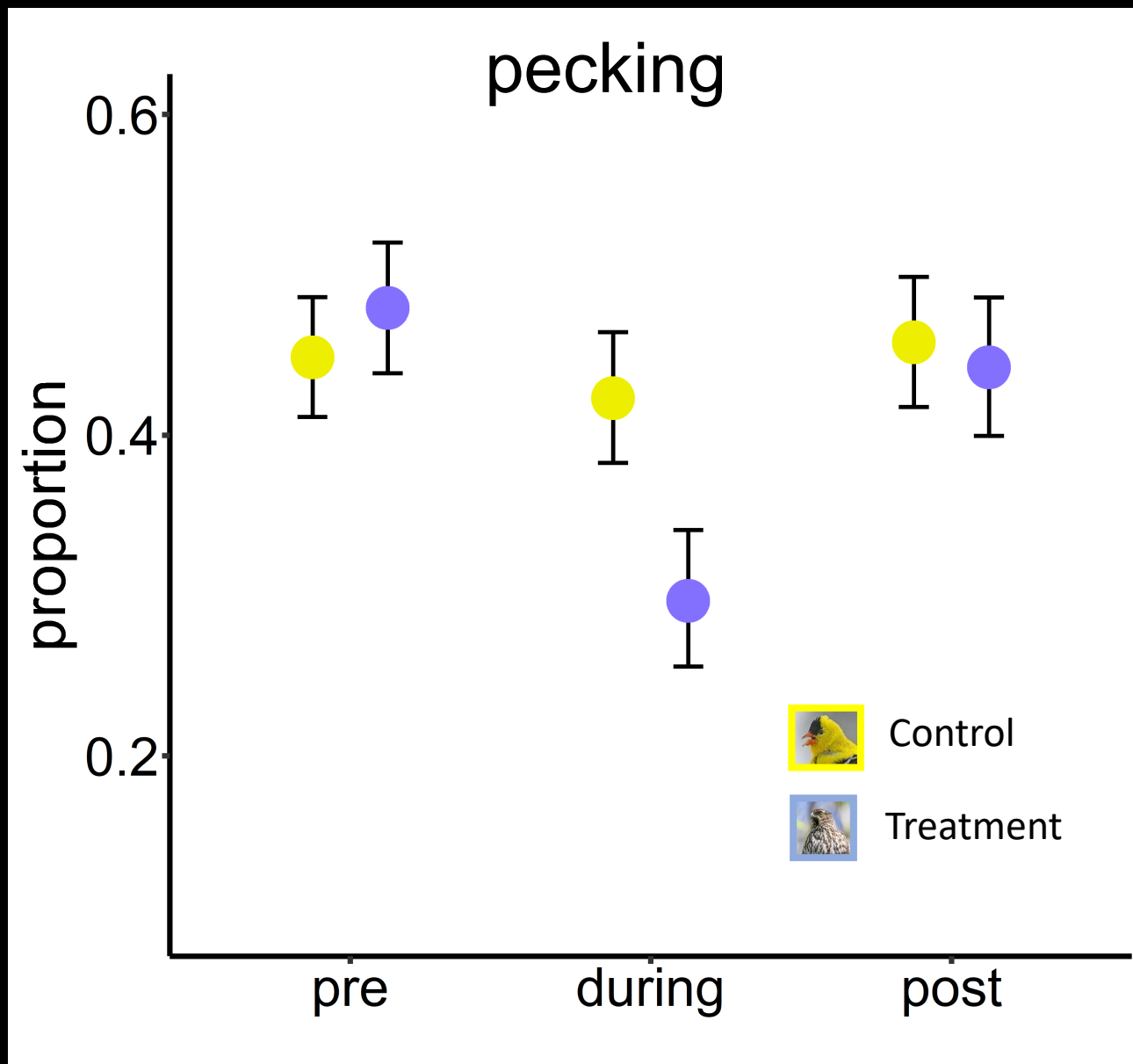


$n = 788$





$n = 788$



Conclusions

Citizen scientists can conduct behavioral experiments

Remote sensing less important, but sample size

Backyard birds important sentinels of predation risk
(vigilance, foraging)

Implications

Predator recovery is a tenant of conservation biology

Citizen science and remote sensing are
critical tools in urban ecology

Untapped potential of citizen science in
behavioral ecology

Wildlife conservation and education in
cities is a critical mission

Acknowledgments

This research would not be possible without
the hard work of thousands of volunteer
FeederWatch participants
(*not passive sensors*)



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